

A Systems Thinking Approach to Eliciting Cybersecurity Requirements for an Electric Snowmobile

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Overview

- Problem Introduction
- Electric Snowmobile Example
- Proposed Value Added
- Future Work
- Questions



Problem Introduction

- Shift from Mechanical to Software based functionality [1]
- Cyber Physical Systems Vehicles, Airplanes, Weapons Systems Vulnerable to Cyber Attacks: [2], [3], [4], [5]
- Acknowledged need to improve Cybersecurity by Design
 - ISACs for Vehicles [6], NDAA requirements for weapons systems [7]
- Need to Improve Requirements Elicitation Process for Security
 - Failure of checklist approach[8]– limits functionality and design trade space
- System Theoretic Process Analysis (STPA) [9], [10], [11]
 - Top-Down Systems Approach
 - Hazard Analysis technique to facilitate requirements for safe and secure complex system design









GAO 2021 Report on Weapon System Cybersecurity

- Contracting for cybersecurity requirements is key.
- DOD guidance states that these requirements should be treated like other types of system requirements
- Specifically, cybersecurity requirements should be defined in acquisition program contracts, and criteria should be established for accepting or rejecting the work and for how the government will verify that requirements have been met.
- GAO found examples of program contracts omitting cybersecurity requirements, acceptance criteria, or verification processes. For example, GAO found that contracts for three of the five programs did not include any cybersecurity requirements when they were awarded.
- A senior DOD official said standardizing cybersecurity requirements is difficult and the department needs to better communicate cybersecurity requirements and systems engineering to the users that will decide whether or not a cybersecurity risk is acceptable.



What GAO Found

Since GAO's 2018 report, the Department of Defense (DOD) has taken action to make its network of high-tech weapon systems less vulnerable to cyberattacks. DOD and military service officials highlighted areas of progress, including increased access to expertise, enhanced cyber testing, and additional guidance. For example, GAO found that selected acquisition programs have conducted, or planned to conduct, more cybersecurity testing during development than past acquisition programs. It is important that DOD sustain its efforts as it works to improve weapon systems cybersecurity.

Contracting for cybersecurity requirements is key. DOD guidance states that these requirements should be treated like other types of system requirements and, more simply, "if it is not in the contract, do not expect to get it." Specifically, cybersecurity requirements should be defined in acquisition program contracts, and criteria should be established for accepting or rejecting the work and for how the government will verify that requirements have been met. However, GAO found examples of program contracts omitting cybersecurity requirements, acceptance criteria, or verification processes. For example, GAO found that contracts for three of the five programs did not include any cybersecurity requirements when they were awarded. A senior DOD official said standardizing cybersecurity requirements is difficult and the department needs to better communicate cybersecurity requirements and systems engineering to the users that will decide whether or not a cybersecurity risk is acceptable.



Incorporating Cybersecurity in Contracts

Concept Analysis





Concept Analysis

<u>A system to convey people and</u> their gear across snow covered mountainous terrain by means of charging, maneuvering, transporting, navigating in order to Provide enjoyment and access to mountainous

snow covered terrain



Can Snowmobiling Really Go Electric?

The beloved winter pastime has long been a massive polluter. Canadian startup Taiga Motors set out to transform the industry into something more environmentally friendly—and the big manufacturers are getting onboard.



Photo Credit: https://www.outsideonline.com/outdooradventure/snow-sports/taiga-motors-electric-snowmobile/



Loss/Hazards Mapping

				Causal Scenarios (Provide V&)
			Lo	SSES
			L1: Loss of reputation/trust with stakeholders	L2: Serious injury or Loss of life
		H1: Lack of range or controls displaying limited range	X	X
		H2: Significant power loss	X	
Photo Credit: Trae Span Original ©	Hazards	H3: Loss of navigation accuracy	X	X
		H4: Other capability degradation	X	X
		H5: Slow or Inaccurate Charging	X	



Initial Requirements (Constraints)

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Hazards	Constraints				
Lack of range or controls displaying limited range	HC-1.1 The system shall have redundant measure of computing range to display accurate and adjusted remaining range to the rider HC-1.2 The system shall conduct self tests on battery capacity and set a warning light when capacity or range calculations are below a minimum threshold				
Significant power loss	 HC-2.1 The system shall incorporate robust tamper and security protections to critical components and software for the drivetrain. HC-2.2 The system shall conduct real time status monitoring and set an indicator light if and when performance parameters exceed certain limits indicating a potential failure mode. HC-2.3 Key system performance metrics must be established and tested for the robustness of indicator lights. 				
Loss of navigation accuracy	HC-3.1 The system shall incorporate multiple sources of navigation aides and set an error message when not aligned. –E.G. Include a compass and barometric pressure sensor for altitude and heading and when over X Degrees or X ft off from GPS readings set an error message for degraded GPS navigation.				
Other capability degradation	HC-4.1 The system shall identify safety critical functionality and prioritze power and onboard resources to maintaining that capability in the face of degradation events				
Slow or Inaccurate Charging	HC-5.1 The system shall comply with applicable SAE Standards for electric vehicle charging HC- 5.2 The system shall monitor charging and display a fault if a charging error occurs				



Architectural Analysis



FIG 1. STPA-SEC TAILORED APPROACH.



Simplified System Architecture Overview



Functional Control Structures (FCS)





FIG 1. STPA-SEC TAILORED APPROACH

Functional Viewpoint FCS

 Uncert Anaptin

 P. Registron

 Provide Contract

 Provide Co

FIG 1 STPA-SEC TAILORED APPROACE





FIG 1. STPA-SEC TAILORED APPROACE

	FIG 1. STPA-SEC TAILORED APPROACH.
	Concept Analysis Propose/Void
	Architectural Analysis Machitectural Analysis Machitectural Analysis Machitectural Analysis General Action General Action
	Increasing Detail Process Model Process Model Process Process Model Process Model Process Process Model Process Process Model Process Process Model Process
low	-

Hazards						Prodvi biologi provide visit of Process] Provide Visit Control (Provide Visit of Process]		
H1: Lack of range or con displaying limited range	trols	H2: Significant power loss	H3: Loss of navigation accuracy	H4: Othe degradat	er capability tion	H5: Inaccurate Charging	or Slow	
Control Action	Not p Haza	providing causes	Providing Causes H	azard	Too Early/too I order	ate, wrong	Stopping too long	too soon/applying
Accelerate (1)	U Acc ope	ICA-#1a : Not Providing celeration is Hazardous if rator requires it to traverse terrain safely [H2, H4]	UCA-#1b : Providing Act Hazardous if in conditio precise navigation with d [H2, H4]	celeration is ons require leceleration	UCA-#1c : Provi too late or too ea in a critical ph navigatior	ding acceleration rly is Hazardous if hase of terrain h [H2, H4]	UCA-#1d : short or too critical ph	Providing acceleration to b long is Hazardous if in a ase of terrain navigation [H2, H4]
UCA-#2a : Not Providing charge is Hazardous if the user requires a charge to continue riding [H-1, H4]		UCA-#2b : Providing Charge is Hazardous if the batteries are in a condition where charging may cause damage (too hot or too cold) [H2, H4, H5]				UCA-#20 hazardous i	c : Charging too long is if it damages the batteries [H2, H4, H5]	
Search Destination (3)	UCA- Des user r	-#3a : Not Providing Searce tination is hazardous if the requires navigation to retu to a safe location [H-3]	ch e rn					
Route Navigation (4)	UCA Nav user i	-#4a : Not Providing Rout rigation is Hazardous if the needs to adjust their path avoid obstacles [H3]	to UCA-#4b : Providing Navigation is Hazardou distracts the user in a maneuver in hazardous [H3]	g Route s if display a critical conditions	UCA-#4c : Not Navigation in a Hazardous if th adjust their path t	Providing Route timely manner is e user needs to to avoid obstacles 13]		
Brake (5)	UCA- Haza to trav	#5a : Not Providing Brake ardous if operator requires verse terrain safely [H2, H	is it I4] UCA-#5b : Providing B Hazardous if in condition precise navigation witho [H2, H4]	oraking is ons require out braking	UCA-#5c : Prov late or too early is critical phase of [H2	iding braking too Hazardous if in a terrain navigation , H4]	UCA-#5d short or too critical ph	: Providing braking too long is Hazardous if in a ase of terrain navigation [H2, H4]

Design Analysis



FIG 1. STPA-SEC TAILORED APPROACH.





- Due to the extensive nature of complex systems, we adapted a streamlined methodology (STPA Handbook)
- Based on the CA Analysis:
 - System Constraints: Derive specific system behaviors that must be satisfied to prevent Unsafe CAs
 - Causal Scenarios: Describes the causal factors that may lead to the Unsafe CAs and to hazards.

N. Leveson and J. Thomas, "An STPA Primer," 9 September 2013. [Online]. Available: http://sunnyday.mit.edu/STPA-Primer-v0.pdf. Reule, Ryyan T., et al. "STPA-Sec Analysis for DevSecOps Reference Design." INCOSE International Symposium. Vol. 31. No. 1. 2021.



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Control Action	Not providing causes hazard	Providing causes hazard	Too early/too late, wrong	Stopping too soon/applying too long
Accelerate (1)	UCA-#1a : Not Providing Acceleration is Hazardous if operator requires it to traverse terrain safely [H2, H4]	UCA-#1b : Providing Acceleration is Hazardous if in conditions require precise navigation with deceleration [H2, H4]	UCA-#1c : Providing acceleration too late or too early is Hazardous if in a critical phase of terrain navigation [H2, H4]	UCA-#1d : Providing acceleration too short or too long is Hazardous if in a critical phase of terrain navigation [H2, H4]
			,	

		Not providing causes hazard	Providing causes hazard	Too early/too late, wrong	Stopping too soon/applying too long
		SC-1.1 Acceleration performance	SC-1.4 More than one	SC 1.4 applies	SC 1.4 applies
		must be continuously montiored	sensor should detect		
		and if degradation is detected a	throttle position and		
		system warning light should be	disagreement between		
		illuminated	sensors should result in		
	Constraints	SC-1.2 If acceleration degradation	the lower value being		
	(Dequirmente)	exceeds a certain thresholds for	selected		
	Requirments)	severity or repetitiveness the			
		system should be placed into a			
		limp mode and notify the operator.			
		SC-1.3 As a safety critical control			
		action the acceleration command			
		should be a part of safety critical			
And a second		security testing.			
	NSRC				17



Control Action 1: Acceleration

Causal Scenario: A malicious actor gains access to the throttle control tables and inverts the percentage of acceleration commanded when the angle of attack exceeds 15 degrees. This security requirement added through STPA supports the necessity of an independent backup sensor for acceleration and code to default to the lower value





Control Action	Not providing causes hazard	Providing causes hazard	Too early/too late, wrong	Stopping too soon/applying too long
Brake (5)	UCA-#5a : Not Providing Brake is Hazardous if operator requires it to traverse terrain safely [H2, H4]	UCA-#5b : Providing braking is Hazardous if in conditions require precise navigation without braking [H2, H4]	UCA-#5c : Providing braking too late or too early is Hazardous if in a critical phase of terrain navigation [H2, H4]	UCA-#5d : Providing braking too short or too long is Hazardous if in a critical phase of terrain navigation [H2, H4]

		Not providing causes hazard	Providing causes hazard	Too early/too late, wrong	Stopping too soon/applying too long
((R	Constraints Requirments)	SC-5.1 Operator should be reminded to verify braking system operation SC-5.2 The braking system should be specified as a 'high reliability' component (specific metrics to be defined further into design)	SC-5.3 The braking system should not automatically engage on decelleration (no regenerative braking when letting off the throttle)	SC 5.2 applies	SC 5.4 The snowmobile should NOT autonomously decide when to apply or release the brakes.





Control Action 5: Brake

Causal Scenario: A software failure, either accidental or malicious, applies brakes when not commanded by the rider. This could easily harm the rider if done at high speeds.

This causal scenario supports a requirement to NOT include regenerative or software controlled braking. This analysis supports a requirement of mechanical only braking.





FC1.STPA-SECTALORED APPROACH.



Possible Extensions?

- Add a Risk Priority Assessment approach to the cyber requirements?
- How do you integrate this with SysMI models?
- Can I use this approach for security policy elicitation?
- Show the impacts of performing this assessment at various levels of abstraction



Questions?



Simplified System Architecture Overview

